

Abstraction and probabilities for hybrid logics

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Abstract

We suggest and develop mathematical foundations for quantitative versions of hybrid logics by means of two related themes. First, we develop relational abstraction techniques for a hybrid computation tree logic and hybrid Kripke structures as an extension of the model-checking framework for computation tree logic with the ability to name, bind, and retrieve states. Second, we propose a syntax and semantics for hybrid probabilistic computation tree logic over hybrid extensions of labelled Markov chains for which the relational abstraction techniques of hybrid Kripke structures should transfer smoothly.

Key words: hybrid logic, model checking, probabilistic system, abstraction.

1 Introduction

Hybrid logics (see e.g. www.hylo.net/) enhance basic modal and temporal logics with the ability to bind names to unique states in models. This extension is an important ability in applications that have to track states or other objects across space or time. If we think of a hybrid logic as a temporal logic enriched with syntactic clauses for the look-up and binding of names, it is natural to ask whether established model-checking methodology can be adapted to, or retained, in this hybrid setting. Apart from the work by Franceschet & Rijke [10], surprisingly little attention has been given to the extension of model

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checking to hybrid temporal logics. We are also not aware of any work on hybrid logics over quantitative or probabilistic models.

This paper therefore provides a modest first step in this direction by developing two model-checking themes for a hybrid extension of computation tree logic [4] : the sound relational abstraction of qualitative models with respect to *all* properties of a hybrid computation tree logic; and the extension of probabilistic systems and probabilistic computation tree logic [12] with hybrid constructs. The connection between these themes is twofold:

- (1) probabilities can be seen as a form of abstraction of qualitative information, reducing the determinism of a system¹; and
- (2) the techniques for relational abstraction of qualitative systems should extend smoothly to probabilistic hybrid systems along the lines of [13].

Note that we only discuss *propositional* temporal logics here.

2 Hybrid computation tree logic

We define a hybrid version of computation tree logic [4] and its models.

- Definition 1** (1) A Kripke structure with signature \mathbf{Obs} is a tuple $M = (\Sigma, R \subseteq \Sigma \times \Sigma, L: \mathbf{Obs} \rightarrow \mathbb{P}(\Sigma))$ where \mathbf{Obs} is a set of atomic observables.
- (2) A hybrid Kripke structure with signature $\mathbf{Obs} = \mathbf{AP} + \mathbf{Nom}$ is a tuple $M = (\Sigma, R \subseteq \Sigma \times \Sigma, L: \mathbf{Obs} \rightarrow \mathbb{P}(\Sigma))$, where \mathbf{AP} and \mathbf{Nom} are disjoint sets of atomic propositions and nominals, respectively, such that for all $n \in \mathbf{Nom}$ the set $L(n)$ contains exactly one element.
- (3) We write (M, i) to denote that state i of M is the initial state of M .

A hybrid Kripke structure consists of a set of states Σ , a state transition relation R , and a labelling function L where, for each observable $o \in \mathbf{Obs}$, $L(o)$ denotes the set of states in Σ at which o holds; see Figure 1. These models are not merely Kripke structures due to the constraints on L : all nominals $n \in \mathbf{Nom}$ hold at *exactly one* state of the model, whereas atomic propositions $p \in \mathbf{AP}$ may hold at no, exactly one, or more than one state. In this paper, we present a hybrid extension of computation tree logic for specifications of properties as this prepares the ground for a hybrid extension of probabilistic computation tree logic [12], but Theorem 10 of this paper adapts to the full propositional mu-calculus [15].

¹ At the same time, probabilities may be seen as concretizations of a “zero-one” non-determinism.

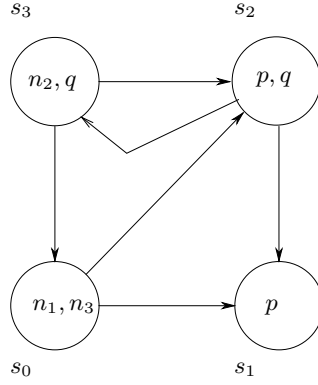


Fig. 1. A hybrid Kripke structure M with signature $\text{Obs} = \{p, q\} + \{n_1, n_2, n_3\}$. A state s is tagged with o iff $s \in L(o)$. In that case, we also write $(M, s) \models o$.

For a signature $\text{Obs} = \text{AP} + \text{Nom}$, an adequate fragment of computation tree logic is

$$\phi ::= \perp \mid o \mid \neg\phi \mid \phi \wedge \phi \mid \text{EX } \phi \mid \text{E}[\phi \text{ U } \phi] \mid \text{AF } \phi \quad (1)$$

where $o \in \text{Obs}$. The temporal patterns $\text{EX } \phi$, $\text{E}[\phi_1 \text{ U } \phi_2]$, and $\text{AF } \phi$ express “At some next state ϕ ,” “On some path ϕ_1 until ϕ_2 ,” and “For all paths, eventually ϕ ,” respectively. Every hybrid Kripke structure M is also a Kripke structure if we “forget” the constraints on the labelling function. So the satisfaction relation $(M, s) \models \phi$ is the familiar one for Kripke structures (e.g. [7]). As usual, we write $\phi \vee \psi$ for $\neg(\neg\phi \wedge \neg\psi)$, and $\phi \rightarrow \psi$ for $\neg(\phi \wedge \neg\psi)$. Moving from Kripke structures to hybrid Kripke structures restricts the class of models and so changes the notions of satisfiability and validity. We discuss two standard examples from the literature.

Example 2 (1) For the computation tree logic formula

$$\text{EX } (n \wedge p) \wedge \text{EX } (n \wedge q) \rightarrow \text{EX } (p \wedge q) \quad (2)$$

we may think of n , p , and q as atomic propositions that can be true at no, one, or more states. Then we can easily find a state in a Kripke structure where this formula is false. If we think of n as being a nominal in a hybrid Kripke structure, the formula is valid. For if the premise is true, then the unique successor state s named by n (i.e. $L(n) = \{s\}$) satisfies p and satisfies q , so there is a successor state satisfying $p \wedge q$.

(2) Using nominals, one also gets a richer correspondence theory between formula and properties of the transition relation. The formula $n \rightarrow \neg\text{EX } n$, interpreted over nominals and Kripke frames² only, expresses that the

² A Kripke frame $F = (\Sigma, R)$ is like a Kripke structure $M = (\Sigma, R, L)$ except that we are not in control of choosing the labelling function L , so $(\Sigma, R) \models \phi$ iff for all L , $(\Sigma, R, L) \models \phi$.

transition relation R is irreflexive; it is known that this property cannot be expressed within modal logic over Kripke frames.

The analysis of hybrid models benefits from enhancing computation tree logic with standard hybrid operators. Let $CTL(@)$ be the extension of computation tree logic with the satisfaction operator $@$

$$\phi ::= \perp \mid o \mid \neg\phi \mid @_n\phi \mid \phi \wedge \phi \mid \mathbf{EX}\phi \mid \mathbf{E}[\phi \mathbf{U}\phi] \mid \mathbf{AF}\phi \quad (3)$$

where $o \in \mathbf{Obs}$ and $n \in \mathbf{Nom}$. The intended meaning of $@_n\phi$ is to “jump” to the unique state $s' \in L(n)$ and evaluate ϕ in that state:

$$(M, s) \models @_n\phi \quad \text{iff} \quad (M, s') \models \phi \text{ for } L(n) = \{s'\}. \quad (4)$$

Note that $(M, s) \models @_n\phi$ either holds in all states of M or in none. This operator is self-dual: $@_n\phi$ and $\neg@_n\neg\phi$ are semantically equivalent over hybrid Kripke structures.

In a hybrid Kripke structure, the labelling function L binds all nominals to a unique state. Viewing nominals as parameters, we can bind them to unique states for the evaluation of formulas. Consider $CTL(\downarrow)$ which adds to computation tree logic the operator $\downarrow n.\phi$, whose semantics requires tagging \models with the labelling function L of the underlying hybrid Kripke structure. For computation tree logic or $CTL(@)$, the evaluation of $(M, s) \models_L \phi$ does not change L . For $CTL(\downarrow)$ the labelling function L changes for the evaluation of clauses of the form $\downarrow n.\phi$.

Definition 3 *Let $L[n \mapsto s]$ be the labelling function with $L[n \mapsto s](o) = L(o)$ for all $o \in \mathbf{Obs}$ with $o \neq n$ and $L[n \mapsto s](n) = \{s\}$. Then we set*

$$(M, s) \models_L \downarrow n.\phi \quad \text{iff} \quad (M, s) \models_{L[n \mapsto s]} \phi. \quad (5)$$

We conclude that model checks for $CTL(\downarrow)$ over the hybrid model M are checks $(M, s) \models_L \phi$ with the initial labelling function of M , but where the evaluation of checks for sub-formulas of the form $\downarrow n.\psi$ updates L statically.

In hybrid logic, the binder $\downarrow n.\phi$ allows one to express that a state s belongs to a cycle (a property *not* expressible in temporal logic) by checking

$$(M, s) \models_L \downarrow n.\mathbf{E}[\neg\perp \mathbf{U} n]. \quad (6)$$

If we think of the labelling algorithm for model checking as an abstract machine, then $@_n\phi$ corresponds to a lookup of “location” n with a continuation that jumps to that located state and evaluates ϕ at that location, whereas

$\downarrow n.\phi$ stores the current location at n and continues with the evaluation of ϕ at the current state.

Finally, consider $CTL(\exists)$ which adds a binder for locations that seems contrary to the locality principle inherent in Kripke’s satisfaction relation \models :

$$(M, s) \models_L \exists n.\phi \quad \text{iff} \quad \text{for some } s' \in \Sigma: (M, s) \models_{L[n \mapsto s']} \phi. \quad (7)$$

The lack of locality of this operator means that no purely bottom-up labelling algorithm for model checking is available. For example, the check $(M, s) \models \exists n.\@_n \mathbf{E}[\neg \perp \cup n]$ holds iff the model M contains *some* cycle, not necessarily through s ; similar problems emerge in a bottom-up evaluation of $\downarrow n.\phi$. In the sequel, we write $CTL(@, \downarrow)$ etc for extensions of CTL with all listed operators.

Example 4 *For the hybrid Kripke structure in Figure 1, the check $(M, s_0) \models_L \@_{n_2} \mathbf{EX} \neg p$ holds since $(M, s_3) \models_L \mathbf{EX} \neg p$. The check $(M, s_0) \models_L \downarrow n_2.\neg \mathbf{EX} n_2$ holds since $(M, s_0) \models_{L[n_2 \mapsto s_0]} \neg \mathbf{EX} n_2$, which holds as $(s_0, s_0) \notin R$. The check $(M, s_0) \models_L \exists n_1.\@_{n_1} \neg p \wedge \mathbf{EX} p$ holds as, e.g., $(M, s_0) \models_{L[n_1 \mapsto s_3]} \@_{n_1} \neg p \wedge \mathbf{EX} p$.*

3 Relational abstraction of hybrid models

The state-explosion problem of model checking, that the size of the state space of a model is typically exponential in the number of atomic propositions, poses a significant challenge to the application of model checking to realistic and scalable problems [7]. This is exacerbated by the fact that the addition of the operators \downarrow or \exists to computation tree logic make the model checking problem PSPACE-complete, although the addition of nominals and $@$ alone does not change the linear complexity of checks in the size of the model [10].

Abstraction is seen as a key technique for mitigating the effect of state-space explosions. Its standard approach [6] abstracts a model via a “safe simulation” such that formulas of linear-time temporal logic or the universal fragment of computation tree logic (“for all paths”) which are true in the abstract model are also true in the concrete one. Counter-examples of the abstract model, however, often are spurious as they do not reflect genuine bugs in the concrete model.

Three-valued model checking [8,2] abstracts concrete models by a “mix” of safe and live simulations such that verifications (“the property holds”) and refutations (“the property does not hold”) of properties on the abstract model apply to the concrete one as well, for temporal logics with unrestricted use of path quantifiers or negation. The price being paid here is that model checks

may have a third result value “unknown” which does not reveal anything about the abstract³ or concrete model.

We see below that the abstraction of hybrid models forces us into the use of 3-valued hybrid models even if we are only concerned with verifying safety properties: the quantifier “for all nominals/paths etc” interacts with the quantifier for the constraints of hybrid models “there is exactly one state” in a way that requires this.

In this section we work with a hybrid Kripke structure $M = (\Sigma, R, L)$ with signature $\mathbf{Obs} = \mathbf{AP} + \mathbf{Nom}$, a set of designated abstract states $\hat{\Sigma}$, and a relation $\rho \subseteq \Sigma \times \hat{\Sigma}$ where $s\rho t$ specifies that state t abstracts s (and, equivalently, that s is a concrete instance of t). We wish to define a hybrid model $\hat{M} = (\hat{\Sigma}, \hat{R}, \hat{L})$ such that ρ is, by construction, a witness to the fact that \hat{M} abstracts M . For that, we assume that ρ is *left-total* and *right-total*:

$$\begin{aligned} \forall s \in \Sigma \exists t \in \hat{\Sigma}: s\rho t \\ \forall t \in \hat{\Sigma} \exists s \in \Sigma: s\rho t \end{aligned} \tag{8}$$

A practically relevant example is $\hat{\Sigma}$ being the set of classes of some partition on Σ , and $s\rho t$ stating $s \in t$. Such partitions could be induced by a finite set of formulas (e.g. boolean guards from program code) on the concrete state space. The abstract structure \hat{M} should satisfy that all verifications, $(\hat{M}, t) \models \phi$, and all refutations, $(\hat{M}, t) \models \neg\phi$, of ϕ in the abstract model apply in the abstracted model (M, s) as well:

$$\forall \phi \in CTL(@, \downarrow, \exists) \forall (s, t) \in \Sigma \times \hat{\Sigma}: s\rho t \ \& \ (\hat{M}, t) \models \phi \Rightarrow (M, s) \models \phi. \tag{9}$$

Securing (9), though, seems to be at odds with the constraints imposed in hybrid models. Let $n \in \mathbf{Nom}$ with $L(n) = \{s_0\}$ and choose any $t \in \hat{\Sigma}$ with $s_0\rho t$. We then face a Catch 22.

- If we rule $t \in \hat{L}(n)$, then $(\hat{M}, t) \models n$ and so (9) implies $(M, s) \models n$ for all s with $s\rho t$. So $\{s \in \Sigma \mid s\rho t\} = \{s_0\}$ has to hold as M is a hybrid Kripke structure. But this cannot be in general; e.g. for partitions this forces t to be a singleton.
- If we rule $t \notin \hat{L}(n)$, then $(\hat{M}, t) \models \neg n$ and (9) imply $(M, s_0) \models \neg n$, contradicting $L(n) = \{s_0\}$.

Note that this dilemma persists if we allow $\hat{L}(n)$ to contain any number of elements or if we restrict (9) to safety properties only and rule $\hat{L}(n) = \{\}$ (as

³ In Bruns & Godefroid’s *generalized* model checking [3] “unknown” reveals that some concretizations of the abstraction do, and some don’t, satisfy the property.

we would have to do in the case of non-trivial partitions). For example, “At all reachable states that satisfy n , all paths eventually reach a state satisfying n ,” holds then trivially in \hat{M} but may well not hold in M as not all paths through the state for n have to lead into a cycle. Three-valued hybrid models are tailored for averting this dilemma.

Definition 5 *A 3-valued hybrid Kripke structure with signature $\text{Obs} = \text{AP} + \text{Nom}$ is a tuple $M = (\Sigma, R^a, R^c, L^a, L^c)$ where (Σ, R^a, L^a) and (Σ, R^c, L^c) are Kripke structures with signature Obs subject to the following constraints:*

- (1) $R^a \subseteq R^c$;
- (2) for all $o \in \text{Obs}$, $L^a(o) \subseteq L^c(o)$; and
- (3) for all $n \in \text{Nom}$, $L^a(n)$ contains at most one element; if so $L^a(n) = L^c(n)$.

The intuition about R^a and L^a , already expressed for labelled transition systems by Larsen & Thomsen in [17], is that they represent “must”-information (“definite,” “necessarily so” etc), whereas $R^c \setminus R^a$ and $L^c(o) \setminus L^a(o)$ denote “may”-information (“possibly,” “could be so” etc). If $L^a(n)$ is non-empty, we force $L^a(n) = L^c(n)$ since no element of $L^c(n) \setminus L^a(n)$ can be refined to be in $L(n)$ for any hybrid Kripke structure that refines this 3-valued hybrid Kripke structure in the sense of Definition 8 below.

This interpretation of “may”- and “must”-information confirms that we can view a hybrid Kripke structure $M = (\Sigma, R, L)$ as the 3-valued hybrid Kripke structure (Σ, R, R, L, L) . Therefore, we may define abstractions on 3-valued hybrid Kripke structure in general, allowing for an incremental abstract-and-refine methodology of 3-valued model checking as in [11].

Definition 6 *For a 3-valued hybrid Kripke structure $A = (\Sigma, R^a, R^c, L^a, L^c)$ with signature $\text{Obs} = \text{AP} + \text{Nom}$, a set $\hat{\Sigma}$, and a left-total and right-total relation $\rho \subseteq \Sigma \times \hat{\Sigma}$ we define a tuple $\hat{A} = (\hat{\Sigma}, \hat{R}^a, \hat{R}^c, \hat{L}^a, \hat{L}^c)$:*

- $(t, t') \in \hat{R}^a$ iff for all spt there is some $s'\rho t'$ with $(s, s') \in R^a$;
- $(t, t') \in \hat{R}^c$ iff for some $(s, s') \in R^c$ we have spt and $s'\rho t'$;
- $t \in \hat{L}^a(o)$ iff for all spt we have $s \in L^a(o)$; and
- $t \in \hat{L}^c(o)$ iff for some spt we have $s \in L^c(o)$.

Example 7 *The 3-valued hybrid Kripke structure \hat{A} of Figure 3 is obtained in this manner from the hybrid Kripke structure A in Figure 2. To see this, we set*

$$\rho = \{(s_0, t_0), (s_1, t_1), (s_2, t_2), (s_3, t_2), (s_4, t_2)\}.$$

Then ρ is left-total and right-total. In \hat{A} , the two transitions (s_0, s_1) and (s_1, s_2) are modelled as solid lines since t_i is only related to s_i for $i = 1, 2$; for the

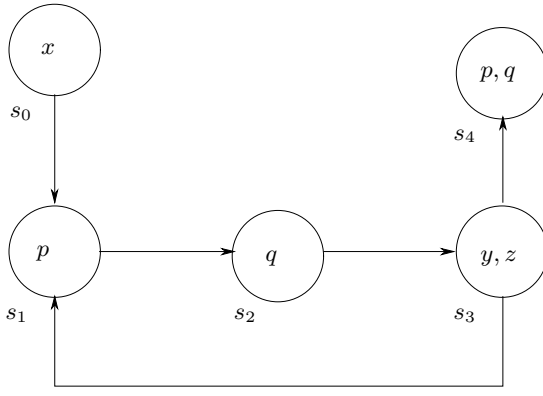


Fig. 2. A shape graph. Nodes are cells in a heap. The set of nominals consists of those program identifiers x , y , and z that do point to a cell in the heap. As no identifier can point to more than one cell at a time we have a hybrid heap model.

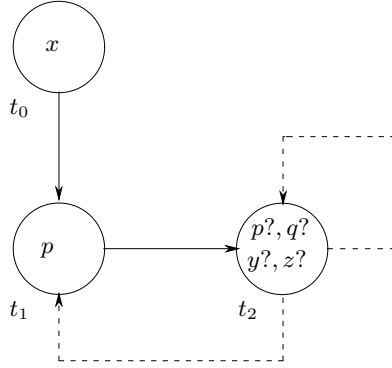


Fig. 3. A 3-valued hybrid Kripke structure that is an abstraction of the hybrid Kripke structure from Figure 2. Solid lines and observables o comprise R^a and $L^a(o)$, respectively. Dashed lines and observables $o?$ comprise $R^c \setminus R^a$ and $L^c(o) \setminus L^a(o)$, respectively.

same reason, their labels x and p are preserved as “must”-information in t_0 and t_1 , respectively. There is a dashed line from t_2 to t_1 because there is a transition (s_3, s_1) , $s_3 p t_2$, and $s_1 p t_1$; but $s_2 p t_2$ and there is no transition out of s_2 to some s with $s p t_1$. Similarly, we account for the dashed transition from t_2 back to itself. No labels at t_2 are “must”-information and all but x are “may”-information. For example, for y this is so since s_3 satisfies y but s_4 doesn’t and both are related to t_2 via p .

This example suggests that hybrid models and logics can express shape graphs [19]. Note how the definitions of \hat{L}^a and \hat{L}^c resolve the dilemma faced for hybrid Kripke structures as abstractions: If A is a hybrid Kripke structure, then $\hat{L}^a(n) = \{t\}$ iff $\{s \in \Sigma \mid s p t\} = L(n)$; and $\hat{L}^c(n)$ contains all those t for which $s_o p t$ where $L(n) = \{s_0\}$.

Before we can show that the abstraction \hat{A} of A in Definition 6 secures (9) we need to present the satisfaction relation \models for a 3-valued hybrid Kripke struc-

ture M in two modes, “ a ” (**asserted**) and “ c ” (**consistent**), where $(M, s) \models^a$ and $(M, s) \models^c$ denote “ ϕ must hold at state s in M ” and “ ϕ may hold at state s in M ,” respectively. If $M = (\Sigma, R, L)$ is a hybrid Kripke structure, then (Σ, R, R, L, L) is a 3-valued hybrid Kripke structure such that \models^a and \models^c are equal and so define \models formally for M . We also define abstraction and refinement formally.

Definition 8 Let $A = (\Sigma, R^a, R^c, L^a, L^c)$ and $\hat{A} = (\hat{\Sigma}, \hat{R}^a, \hat{R}^c, \hat{L}^a, \hat{L}^c)$ be two 3-valued hybrid Kripke structures with signature $\text{Obs} = \text{AP} + \text{Nom}$.

- (1) A relation $Q \subseteq \Sigma \times \hat{\Sigma}$ is a refinement iff $(s, t) \in Q$ implies
 - (a) for all $(t, t') \in \hat{R}^a$, there is some $(s, s') \in R^a$ with $(s', t') \in Q$;
 - (b) for all $(s, s') \in R^c$, there is some $(t, t') \in \hat{R}^c$ with $(s', t') \in Q$;
 - (c) for all $o \in \text{Obs}$, $t \in \hat{L}^a(o)$ implies $s \in L^a(o)$; and
 - (d) for all $o \in \text{Obs}$, $s \in L^c(o)$ implies $t \in \hat{L}^c(o)$.
- (2) We say that (\hat{A}, t) abstracts (is refined by) (A, s) iff there is a refinement Q with $(s, t) \in Q$.
- (3) For $s \in \Sigma$ and $n \in \text{Nom}$, the labelling function $L[n \mapsto^a s]$ is L except for n , where $L[n \mapsto^a s]^a(n) = L[n \mapsto^a s]^c(n) = \{s\}$; the labelling function $L[n \mapsto^c s]$ is L except for n , where $L[n \mapsto^c s]^c(n) = L^c(n) \cup \{s\}$ and $L[n \mapsto^a s]^a(n) = \{\}$.
- (4) We define \models_L^a and \models_L^c for 3-valued hybrid Kripke structures, where $m \in \{a, c\}$, $\neg a = c$, and $\neg c = a$:
 - $(A, s) \not\models_L^m \perp$;
 - $(A, s) \models_L^m o$ iff $s \in L^m(o)$;
 - $(A, s) \models_L^m \neg \phi$ iff $(A, s) \not\models_L^m \phi$;
 - $(A, s) \models_L^m @_n \phi$ iff there is some $s' \in L^m(n)$ with $(A, s') \models_L^m \phi$;
 - $(A, s) \models_L^m \downarrow n. \phi$ iff $(A, s) \models_{L[n \mapsto^m s]}^m \phi$;
 - $(A, s) \models_L^m \exists n. \phi$ iff there is some s' with $(A, s) \models_{L[n \mapsto^m s']}^m \phi$;
 - $(A, s) \models_L^m \phi_1 \wedge \phi_2$ iff $(A, s) \models_L^m \phi_1$ and $(A, s) \models_L^m \phi_2$;
 - $(A, s) \models_L^m \text{EX} \phi$ iff there is some $(s, s') \in R^m$ such that $(A, s') \models_L^m \phi$;
 - $(A, s) \models_L^m \text{E}[\phi_1 \cup \phi_2]$ iff there is some $0 \leq j$ and $(s_k, s_{k+1}) \in R^m$ for all $k \in \{0, 1, \dots, j-1\}$ such that $s = s_0$, $(A, s_k) \models_L^m \phi_1$ for all $k \in \{0, 1, \dots, j-1\}$, and $(A, s_j) \models_L^m \phi_2$; and
 - $(A, s) \models_L^m \text{AF} \phi$ iff there is no infinite sequence $(s_i)_{i \geq 0}$ with $s = s_0$, $(s_k, s_{k+1}) \in R^m$ for all $k \geq 0$, and $(A, s_k) \not\models_L^m \phi$ for all $k \geq 0$.

Remark 9 The ability to jump to arbitrary states in which to continue the evaluation of model checks means that (9) cannot be secured by just showing that the abstract state t indeed abstracts the concrete one s . Sound abstraction becomes a global property in that we need left-total and right-total refinement relations, which are thankfully closed under composition and subsume all state space partitions.

The effect of $\hat{L}[n \mapsto^a t]$ in \hat{A} is a “must”-bind n of to t ; and the effect of $L[n \mapsto^c s]$

is a “may”-bind of n to s . Both actions constrain the un-abstracted “may-” and “must-” bindings of n in A conservatively.

Theorem 10 (1) Let $A = (\Sigma, R^a, R^c, L^a, L^c)$ and $\hat{A} = (\hat{\Sigma}, \hat{R}^a, \hat{R}^c, \hat{L}^a, \hat{L}^c)$ be two 3-valued hybrid Kripke structures with signature $\text{Obs} = \text{AP} + \text{Nom}$ and a left-total and right-total refinement $Q \subseteq \Sigma \times \hat{\Sigma}$ such that $(s, t) \in Q$. For all formulas $\phi \in \text{CTL}(@, \downarrow, \exists)$ we have that $(\hat{A}, t) \models_{\hat{L}}^a \phi$ implies $(A, s) \models_L^a \phi$; and $(A, s) \models_L^c \phi$ implies $(\hat{A}, t) \models_{\hat{L}}^c \phi$.

(2) Let A be a 3-valued hybrid Kripke structure and \hat{A} defined from A as in Definition 6 for a left-total and right-total ρ . Then \hat{A} is a 3-valued hybrid Kripke structure and for all s, t , (\hat{A}, t) abstracts (A, s) . In particular, item (1) applies.

PROOF.

- (1) We prove item (1) by structural induction on ϕ . We focus on the clauses o , $@_n \phi$, $\downarrow n. \phi$, and $\exists n. \phi$ as the proofs for the remaining clauses are standard (see e.g. [8,2,14]).
- Let $(\hat{A}, t) \models_{\hat{L}}^a n$. Then $t \in \hat{L}^a(n)$. From $(s, t) \in Q$ we infer $s \in L^a(n)$ which implies $(A, s) \models_L^a n$.
 - Let $(A, s) \models_L^c n$. Then $s \in L^c(n)$. From $(s, t) \in Q$ we infer $t \in \hat{L}^c(n)$ which implies $(\hat{A}, t) \models_{\hat{L}}^c n$.
 - Let $(\hat{A}, t) \models_{\hat{L}}^a @_n \phi$. Then there is some t' with $t' \in \hat{L}^a(n)$ and $(\hat{A}, t') \models_{\hat{L}}^a \phi$. Since Q is right-total, there is some s' with $(s', t') \in Q$ and so $t' \in \hat{L}^a(n)$ implies $s' \in L^a(n)$. By induction, $(s', t') \in Q$ and $(\hat{A}, t') \models_{\hat{L}}^a \phi$ imply $(A, s') \models_L^a \phi$. But then $s' \in L^a(n)$ implies $(A, s) \models_L^a @_n \phi$.
 - Let $(A, s) \models_L^c @_n \phi$. Then there is some s' with $s' \in L^c(n)$ and $(A, s') \models_L^c \phi$. Since Q is left-total, there is some t' with $(s', t') \in Q$ and so $s' \in L^c(n)$ implies $t' \in \hat{L}^c(n)$. By induction, $(s', t') \in Q$ and $(A, s') \models_L^c \phi$ imply $(\hat{A}, t') \models_{\hat{L}}^c \phi$. But then $t' \in \hat{L}^c(n)$ implies $(\hat{A}, t) \models_{\hat{L}}^c @_n \phi$.
 - Let $(\hat{A}, t) \models_{\hat{L}}^a \downarrow n. \phi$. Then $(\hat{A}, t) \models_{\hat{L}[n \mapsto^a t]}^a \phi$. If we replace \hat{L} with $\hat{L}[n \mapsto^a t]$ and L with $L[n \mapsto^a s]$ in \hat{A} and A (respectively), then the assumptions of item (1) still hold. By induction, $(\hat{A}, t) \models_{\hat{L}[n \mapsto^a t]}^a \phi$ therefore implies $(A, s) \models_{L[n \mapsto^a s]}^a \phi$ and so $(A, s) \models_L^a \downarrow n. \phi$.
 - Let $(A, s) \models_L^c \downarrow n. \phi$. Then $(A, s) \models_{L[n \mapsto^c s]}^c \phi$. If we replace \hat{L} with $\hat{L}[n \mapsto^c t]$ and L with $L[n \mapsto^c s]$ in \hat{A} and A (respectively), then the assumptions of item (1) still hold. By induction, $(A, s) \models_{L[n \mapsto^c s]}^c \phi$ therefore implies $(\hat{A}, t) \models_{\hat{L}[n \mapsto^c t]}^c \phi$ and so $(\hat{A}, t) \models_{\hat{L}}^c \downarrow n. \phi$.
 - Let $(\hat{A}, t) \models_{\hat{L}}^a \exists n. \phi$. Then there is some t' with $(\hat{A}, t) \models_{\hat{L}[n \mapsto^a t']}^a \phi$. Since Q is right-total, there is some s' with $(s', t') \in Q$. If we replace \hat{L} with $\hat{L}[n \mapsto^a t']$ and L with $L[n \mapsto^a s']$ in \hat{A} and A (respectively), then

the assumptions of item (1) still hold. By induction, $(\hat{A}, t) \models_{\hat{L}[n \rightarrow a t']}^a \phi$ therefore implies $(A, s) \models_{L[n \rightarrow a s']}^a \phi$ and so $(A, s) \models_L^a \exists n. \phi$.

- Let $(A, s) \models_L^c \exists n. \phi$. Then there is some s' with $(A, s) \models_{L[n \rightarrow c s']}^c \phi$. Since Q is left-total, there is some t' with $(s', t') \in Q$. If we replace \hat{L} with $\hat{L}[n \rightarrow c t']$ and L with $L[n \rightarrow c s']$ in \hat{A} and A (respectively), then the assumptions of item (1) still hold. By induction, $(A, s) \models_{L[n \rightarrow c s']}^c \phi$ therefore implies $(\hat{A}, t) \models_{\hat{L}[n \rightarrow c t']}^c \phi$ and so $(\hat{A}, t) \models_L^c \exists n. \phi$.

(2) This is the case by construction.

Example 11 *Let us re-consider the hybrid Kripke structure A of Figure 2 and its abstraction \hat{A} of Figure 3.*

- (1) *We have $(\hat{A}, t_2) \models_{\hat{L}}^a @_x \mathbf{E}[x \vee p \mathbf{U} \neg x]$ since we have $(\hat{A}, t_0) \models_{\hat{L}}^a \mathbf{E}[x \vee p \mathbf{U} \neg x]$, where the latter is witnessed by the \hat{R}^a -path $t_0 \rightarrow t_1 \rightarrow t_2$. Since $s_4 p t_2$, Theorem 10 entails that $(A, s_4) \models_L @_x \mathbf{E}[x \vee p \mathbf{U} \neg x]$.*
- (2) *Finally, we have $(\hat{A}, t_2) \models_{\hat{L}}^c \mathbf{E}[y \mathbf{U} \neg p]$ since $t_2 \in L^c(p) \setminus L^a(p)$, but don't have $(A, s_4) \models_L^c \mathbf{E}[y \mathbf{U} \neg p]$ despite the fact that $s_4 p t_2$. The direction of transfer of model-checking results is therefore mode-dependent.*

4 Hybrid labelled Markov chains

Hybrid logics enrich temporal logics and their models with the ability to name and therefore track states in a model. For Kripke structures and computation tree logic, this enrichment required a multiplicity constraint on the labelling function, which had to be relaxed in abstraction-based model checking, and the addition of hybrid operators to computation tree logic. In moving from qualitative hybrid logics to quantitative and probabilistic ones, several questions emerge:

- (1) How do or should hybrid operators generalize to a quantitative or probabilistic setting?
- (2) Are model-checking back-ends and their data-structures (e.g. MTBBDs [5,1], Kronecker Representation [18,9]) affected by the addition of hybrid operators, and if so how?
- (3) Do relational abstraction techniques for qualitative hybrid models transfer smoothly to the quantitative or probabilistic setting?
- (4) What is the complexity of model checking hybrid extensions of labelled Markov chains over hybrid extensions of probabilistic computation tree logic? It is worse than the one for the non-hybrid setting?

We give *very* preliminary answers to these questions in this paper, essentially, we focus on the first question as it is the natural starting point of such a

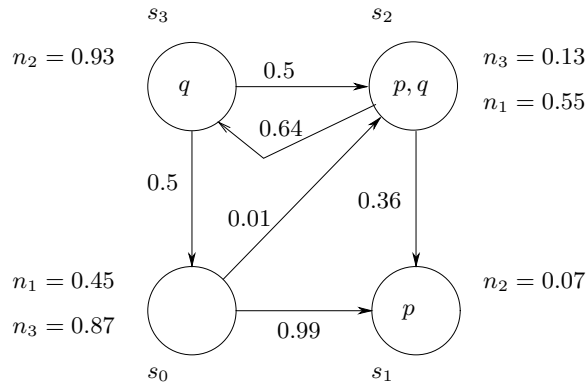


Fig. 4. A hybrid labelled Markov chain with signature $\text{Obs} = \{p, q\} + \{n_1, n_2, n_3\}$. Probabilities of nominals are depicted next to the respective states. For example, $L(n_3, s_0) = 0.87$ and $L(n_3, s_3) = 0$.

programme. For sake of illustration, we focus on finite-state labelled Markov chains and probabilistic computation tree logic without “bounded until,” e.g. as used in [1].

- Definition 12** (1) A (finite-state) labelled Markov chain with signature Obs is a tuple $M = (\Sigma, R: \Sigma \times \Sigma \rightarrow [0, 1], L: \text{Obs} \rightarrow \mathbb{P}(\Sigma))$ where Obs is a set of atomic observables; for all $s \in \Sigma$, $\sum_{s' \in \Sigma} R(s, s') = 1$; and Σ and L have the same interpretation as for Kripke structures.
- (2) A hybrid labelled Markov chain with signature $\text{Obs} = \text{AP} + \text{Nom}$ is a tuple $M = (\Sigma, R: \Sigma \times \Sigma \rightarrow [0, 1], L: (\text{AP} \rightarrow \mathbb{P}(\Sigma)) + (\text{Nom} \times \Sigma \rightarrow [0, 1]))$ where $(\Sigma, R, L|_{\text{AP}})$ is a labelled Markov chain⁴; AP and Nom are disjoint sets of atomic propositions and nominals, respectively; and for all $n \in \text{Nom}$, $\sum_{s \in \Sigma} L(n, s) = 1$.

In a hybrid labelled Markov chain, the labelling function L has a sum type: as is the case in labelled Markov chains, $L(a)$ denotes those states of Σ in which atomic observable $a \in \text{AP}$ holds; whereas $\lambda s.L(n, s)$ is the probability distribution of the nominal n in the state space Σ ; see Figure 4 for a version of the hybrid Kripke structure from Figure 1 as a hybrid labelled Markov chain.

We treat nominals probabilistically as the function $\lambda s.L(n, s)$ is a probability distribution over the set of states for each nominal $n \in \text{Nom}$. Such a type is of interest as it models *probabilistic uncertainty of an observable agent’s whereabouts*. But it also allows us to retain the original intent of hybrid logics by choosing $\lambda s.L(n, s)$ to be a point distribution $\delta_{s'}$ which assigns 1 to s' and 0 to all other states. Alternatively, one could choose other quantitative measures (risks, costs etc) so that $\sum_{s \in \Sigma} L(n, s)$ is no longer 1. The unifying point of such choices is that information about nominals is often uncertain or incomplete.

⁴ We write $L|_{\text{AP}}$ to denote the restriction of L to type $\text{AP} \rightarrow \mathbb{P}(\Sigma)$.

Now we discuss what a suitable hybrid probabilistic temporal logic may look like. The probabilistic temporal logic PCTL, probabilistic computation tree logic (without bounded until),

$$\phi ::= \perp \mid a \mid \neg\phi \mid \phi \wedge \phi \mid [X\phi]_{\sqsupseteq p} \mid [\phi \cup \phi]_{\sqsupseteq p} \quad (10)$$

is due to Hansson [12] where $a \in \mathbf{AP}$, $p \in [0, 1]$, and $\sqsupseteq \in \{\geq, >\}$. Below we extend the familiar semantics of probabilistic computation tree logic over labelled Markov chains to our hybrid setting. This interpretation suggests probabilistic variants of the hybrid operators $@_n \phi$, $\downarrow n.\phi$, and $\exists n.\phi$:

The check $(M, s) \models_L @_n^{\sqsupseteq p}.\phi$ could perhaps hold if $\sum\{L(n, s') \mid (M, s') \models_L \phi\} \sqsupseteq p$. This interpretation is similar to the one for $[X\phi]_{\sqsupseteq p}$, expect that the state “transition” probabilities are governed by the probability distribution $\lambda s.L(n, s)$ instead of the probability distribution $\lambda s'.R(s, s')$. Nonetheless, such a semantics is computable with standard techniques from symbolic model checking of Markov chains, e.g. as implemented in the PRISM model checker [16]. Yet this interpretation is at odds with the role of conditional probabilities: Since $L(n, s')$ is the probability of n 's being at state s' , we wish to sum up all such weights for which the continuation check is true at s' under the assumption that “nominal n resides at state s' ,” so we have to set

$$(M, s) \models_L @_n^{\sqsupseteq p}.\phi \quad \text{iff} \quad \sum\{L(n, s') \mid (M, s') \models_{L[n \rightarrow \delta_{s'}]} \phi\} \sqsupseteq p. \quad (11)$$

Unlike in the qualitative case, checks of $@_n^{\sqsupseteq p}$ statically change the labelling function for the check of sub-formulas. Although this requires adaptations of existing algorithms for probabilistic model checking, the good news is that the continuation resolves the labelling information for n to a qualitative observable as found in a labelled Markov chain.

The qualitative check $(M, s) \models_L \downarrow n.\phi$ holds iff $(M, s) \models_{L[n \rightarrow \delta_s]} \phi$ holds. Given that, we may as well assign probability distributions other than point distributions to the continuation of a probabilistic check:

$$(M, s) \models_L \downarrow(n, \delta).\phi \quad \text{iff} \quad (M, s) \models_{L[n \rightarrow \delta]} \phi. \quad (12)$$

The qualitative check $(M, s) \models_L \exists n.\phi$ holds iff for some $s' \in \Sigma$, $(M, s) \models_{L[n \rightarrow \delta_{s'}]} \phi$ holds. If we set $\Delta' = \{\delta_{s'} \mid s' \in \Sigma\}$, this is an instance of a general probabilistic check

$$(M, s) \models_L \exists(n, \Delta').\phi \quad \text{iff} \quad \text{for some } \delta \in \Delta': (M, s) \models_{L[n \rightarrow \delta]} \phi. \quad (13)$$

For this operator $\phi \mapsto \exists(n, \Delta').\phi$ we may have to restrict the range of Δ' in order to make it computable or even feasibly so. We judge such extensions of

probabilistic computation tree logic to be of potentially great use. For example, the idea of using probability distributions to model the presence of agents suggests applications in security.

This generality of probabilistic hybrid operators may not honor the original intent of hybrid temporal patterns. For example, $(M, s) \models_L \downarrow(n, \delta).[\neg \perp U n]_{\geq .9999}$ checks whether the node named by n is on a *probabilistic* cycle with probability at least .9999 *only* if the probability distribution δ does not smear the location of such a node, i.e. only if it is of the form $\delta_{s'}$ for some $s' \in \Sigma$. Using point distributions, probabilistic hybrid logics are therefore able to express a kind of *probabilistic recurrence* of probabilistic trace sets.

5 Hybrid Probabilistic Computation Tree Logic

We summarize our discussion into a proposal for a hybrid probabilistic computation tree logic:

Definition 13 *Let $\text{Obs} = \text{AP} + \text{Nom}$ be a signature for hybrid labelled Markov chains and Δ a class of discrete probability distributions subsuming all point distributions. Then hybrid probabilistic computation tree logic, without the bounded until, over Obs and Δ is defined by*

$$\begin{aligned} \phi ::= & \perp \mid a \mid \neg\phi \mid \phi \wedge \phi \mid [X\phi]_{\exists p} \mid [\phi U \phi]_{\exists p} \quad (14) \\ & n^{\exists p} \mid @^{\exists p} n.\phi \mid \downarrow(n, \delta).\phi \mid \exists(n, \Delta').\phi \end{aligned}$$

where $a \in \text{AP}$, $n \in \text{Nom}$, $p \in [0, 1]$, $\exists \in \{\geq, >\}$, $\delta \in \Delta$, and $\Delta' \subseteq \Delta$.

The qualitative operators $\downarrow n.\phi$ and $\exists n.\phi$ are derived in that $(M, s) \models_L \downarrow n.\phi$ is interpreted as $(M, s) \models_L \downarrow(n, \delta_s).\phi$; and $(M, s) \models_L \exists n.\phi$ as $(M, s) \models_L \exists(n, \{\delta_s \mid s \in \Sigma\}).\phi$.

Let $M = (\Sigma, R, L)$ be a hybrid labelled Markov chain with signature Obs . We define $(M, s) \models_L \phi$ for all ϕ of hybrid probabilistic computation tree logic. Given $s \in \Sigma$, let $\text{Path}(s)$ be the set of infinite paths in M beginning in s , where transitions $s \rightarrow s'$ occur iff $R(s, s') > 0$. Given ϕ , ϕ_1 , and ϕ_2 of hybrid probabilistic computation tree logic and some $\pi \in \text{Path}(s)$ we define

- $\pi \models_L X \phi$ iff $(M, s') \models_L \phi$, where $\pi = s \rightarrow s' \rightarrow \dots$;
- $\pi \models_L \phi_1 U \phi_2$ iff there is some $k \geq 1$ such that the first $k - 1$ states s_i of π satisfy $(M, s_i) \models_L \phi_1$ and the k th state s_k satisfies $(M, s_k) \models_L \phi_2$.

So we define \models_L over certain path formulas and all state formulas of hybrid probabilistic computation tree logic by mutual induction, as done for probabilistic computation tree logic [12]. The semantics for \perp , a , negation, and conjunction is defined as for Kripke structures. The semantics for the path formulas and hybrid operators is

- $(M, s) \models_L [X\phi]_{\supset p}$ iff the probability of the set of those $\pi \in Path(s)$ with $\pi \models_L X\phi$ is $\supset p$;
- $(M, s) \models_L [\phi_1 U \phi_2]_{\supset p}$ iff the probability of the set of those $\pi \in Path(s)$ with $\pi \models_L \phi_1 U \phi_2$ is $\supset p$;
- $(M, s) \models_L n^{\supset p}$ iff $L(n, s) \supset p$;
- $(M, s) \models_L @^{\supset p} n. \phi$ iff $\sum \{L(n, s') \mid (M, s') \models_{L[n \mapsto \delta_{s'}]} \phi\} \supset p$;
- $(M, s) \models_L \downarrow(n, \delta). \phi$ iff $(M, s) \models_{L[n \mapsto \delta]} \phi$; and
- $(M, s) \models_L \exists(n, \Delta'). \phi$ iff for some $\delta \in \Delta'$, we have $(M, s) \models_{L[n \mapsto \delta]} \phi$.

We remark that \models_L is well defined for all finite-state hybrid labelled Markov chains since all path formulas over predicates (the sets of states for which a particular formula of hybrid probabilistic computation tree logic is true) give rise to measurable path sets [20]. The semantics for path formulas is as for probabilistic computation tree logic.

Example 14 *To illustrate our semantics of hybrid probabilistic computation tree logic, we check $(M, s_3) \models_L @_{n_3}^{>0.1} [\neg \perp U n_3]_{\geq 0.01}$. For that, we need to determine for which s with $L(n_3, s) > 0$ we have $(M, s) \models_{L[s \mapsto \delta_s]} [\neg \perp U n_3]_{\geq 0.01}$; and then sum up all those $L(n_3, s)$ and check whether that sum is > 0.1 . Only s_0 and s_2 are relevant here.*

- *At state s_0 in M with labelling function $L[n_3 \mapsto \delta_{s_0}]$ the probability that s_0 is on a cycle is $0.01 \cdot 0.64 \cdot 0.5 \cdot (\sum_{i=0}^{\infty} (0.64 \cdot 0.5)^i) = 0.00948529 \dots$ which is not ≥ 0.01 and so $(M, s_0) \models_{L[s \mapsto \delta_{s_0}]} [\neg \perp U n_3]_{\geq 0.01}$ does not hold, meaning that $L(s_0, n_3) = 0.87$ does not contribute to that sum.*
- *At state s_2 in M with labelling function $L[n_3 \mapsto \delta_{s_2}]$ the probability that s_2 is on a cycle is $0.64 \cdot 0.5 + 0.64 \cdot 0.5 \cdot 0.01 = 0.3232$ which is ≥ 0.01 and so $(M, s_2) \models_{L[s \mapsto \delta_{s_2}]} [\neg \perp U n_3]_{\geq 0.01}$ holds, meaning that $L(s_2, n_3) = 0.13$ is the only contributor to the sum.*

Since $0.13 > 0.1$, we conclude that $(M, s_3) \models_L @_{n_3}^{>0.1} [\neg \perp U n_3]_{\geq 0.01}$ holds.

6 Conclusions

We presented propositional hybrid logics as established enhancements of propositional temporal logics with the ability to name and re-bind specific states. We then provided a sound relational abstraction technique for hybrid Kripke

structures and a hybrid version of computation tree logic. We further motivated and discussed a definition of hybrid labelled Markov chains and a syntax and semantics of probabilistic computation tree logic in this hybrid setting. Our abstraction techniques for hybrid Kripke structures should transfer smoothly to hybrid labelled Markov chains and *quantitative* hybrid models along the lines of [13]. We note that nominals and their retrieval operators $@_n^{\exists^p} \phi$ do not increase the complexity of probabilistic model checking, but a worst-case increase is likely for the binders $\downarrow(n, \delta). \phi$ or $\exists(n, \Delta'). \phi$.

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